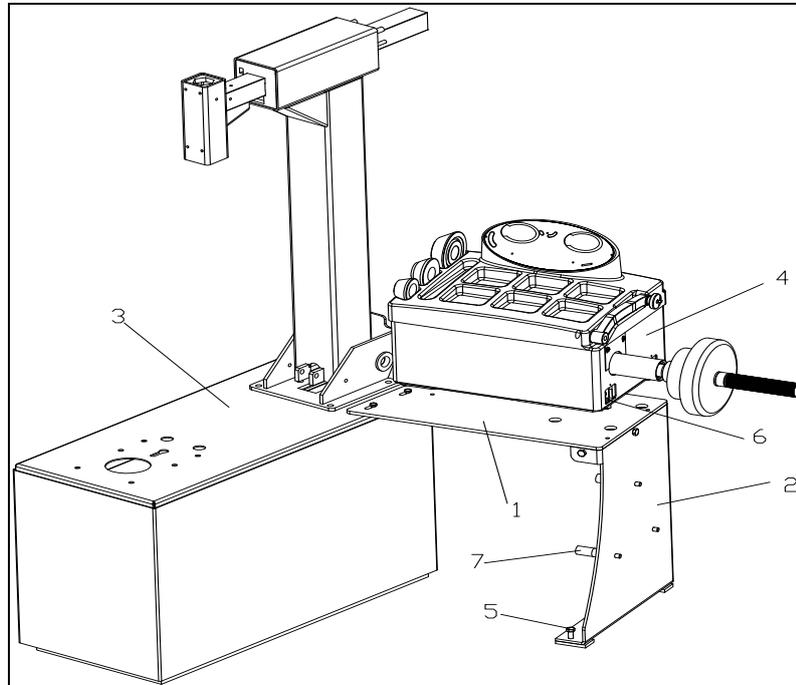


TC-1261 ALL-IN-ONE Tyre Changer & Wheel Balancer



1. As shown in figure, assemble the base plate (1) and the bracket (2) with three pieces M10 bolts, and then fixed the base plate (1) on the tyre changer (3) with two pieces M10 bolts.
2. Adjust the bolt (5) to make the base plate (1) at the horizontal.
3. Put the wheel balancer (4) on the base plate (1), and make the mounting holes aligned. Fix them with 3 pieces M8 bolts
4. Installed the tools hang (7) on the bracket (2).

| NO | Parts' Name | Parts' Code | NO | Parts' Name | Parts' Code |
|----|----------------|------------------|----|-------------|----------------|
| 1 | Base plate | PX-110M-020600-0 | 5 | Bolt | M10*25 |
| 2 | Bracket | PX-110M-020700-0 | 6 | Bolt | M8*30 |
| 3 | Tyre changer | U-2022 | 7 | Tools hang | P-000-009000-0 |
| 4 | Wheel balancer | U-110 | | | |

TYRE CHANGER
INSTRUCTION & MAINTENANCE MANUAL

We follow the way that wheel moving!



Read this entire manual carefully and completely
before installation or operation of the tire changer

TYRE CHANGER INSTRUCTION MANUAL

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Tyre Changer

Warning

This instruction manual is important for the machine, please read carefully before installation and use; also it is important for safe use and machine maintenance of machine. Please keep this manual properly in order to further maintenance of the machine.

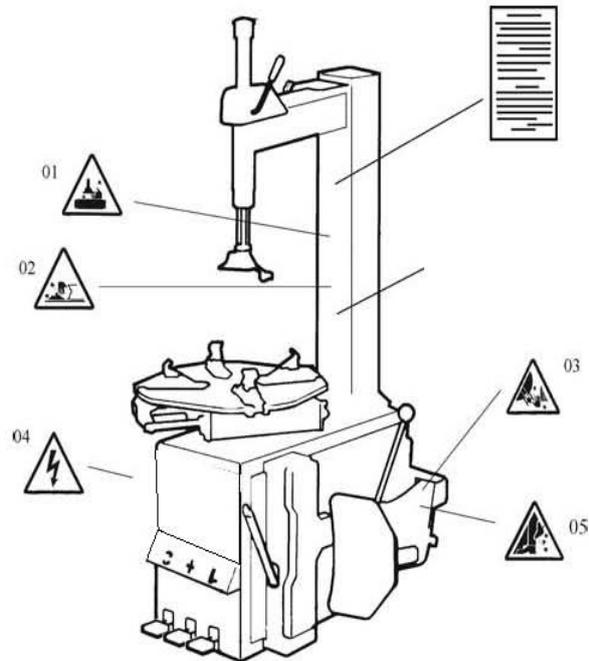
1. Introduction:

Application Range: The semi-automatic tyre changer is especially designed for demounting / mounting tyres from wheel rims.

Caution: Please use the machine only for purpose for which it is designed, don't use it for other purposes.

Manufacturer shall not be liable for any damage or injury caused by failure to comply with these regulations.

Safety regulation: Use of this machine is especially reserved to trained and qualified professional persons, those who already read the introduction manual carefully, or someone have the experience for operating similar machinery. Any changes and beyond the scope of use on this machine without manufacturer's permission or do not according to the manual, may cause the malfunction and damage to machine, manufacturer can cancel warranty coverage for above. If some parts are damaged due to some reason, please replace them according to the spare parts list. (Attention: warranty is one year after manufactures' delivery date; warranty excludes the easy-broken parts).



2. Warning label and sticking position:

- 01 Don't put hands under the Mounting/demounting head during operation;
- 02 Don't put hands between the jaws during operation;
- 03 Don't put hands inside the tyre bead when demounting the tyre;
- 04 Make sure and to check the system is equipped with a good grounding circuit;
- 05 Don't put feet between the Bead Breaker shovel and the body during operation;

Security warning labels

Caution:

When the security warning labels are defaced or off, please recovery them in time!

Do not allow to operate when the security warning labels are missed or imperfect. Do not allow to set any objects to obscure the security warning labels.



Clients can self-set the warning labels (as right picture show) at any necessary positions.

3. Technical data

| | |
|----------------------------------|------------------------------------|
| External locking rim dimensions | 10~21 " |
| Internal locking rim dimensions | 12~24 " |
| Max. Wheel diameter | 1040mm(41 ") |
| Max. Wheel width | 355mm(14 ") |
| Working Pressure | 8-10bar |
| Power supply | 110V (1ph)/ 220V (1ph)/ 380V (3ph) |
| Optional Motor power | 0.75/0.55/1.1 kw |
| Max. Rotating Torque (Turntable) | 1078 Nm |
| Overall Dimension | 96*76*93cm |
| Noise Level | 75dB |

Remark:

Rim dimensions defined at above table are based on the iron wheel rims. Aluminum rims are thicker than the iron wheel rims, so here above rim dimensions are just for the reference.

Here above machine versions can be equipped with Rapid Tire Inflation Device (client optional device), IT-suffix version, accessory details can be found at the IT-suffix version exploded drawing.

4. Transport:

When transporting, the machine should be with original package and placed according to the mark on the package. For the already packaged machine should be handled with a corresponding tonnage forklift for loading and unloading. The location to insert the fork feet shown as Fig 1

5. Unpacking & Inspection:

Pull out the nail which is nailed on the plate with tip jaw; unpack the carton and plastic cover. Check and make sure all parts shown on the spare parts list are included. If any parts are missing or broken, please do not use the machine and contact the manufacturer or dealer ASAP.

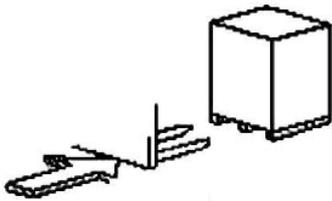


Fig 1

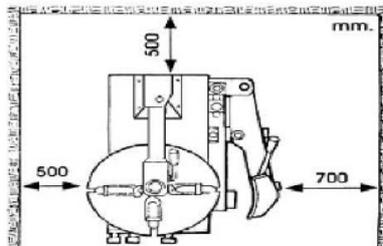


Fig 2

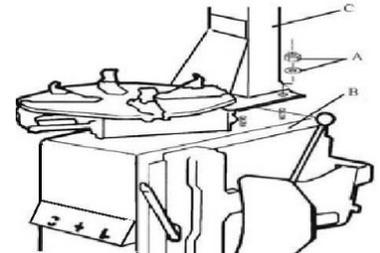


Fig 3

6. Workplace requirements:

Choose workplace in compliance with safety regulations. Connect power supply and air source according to manual and workplace must have good air condition; in order to make the machine run well, its workplace requires at least clear space from each wall shown as Fig 2. If installing it outdoor, it must be protected by roof against rain and sunshine.

Warning: the machine with motor must not be operated in explosive atmosphere.

7. Position and installation:

1. Unscrew the nuts at the bottom, position the machine and calibrate it with the horizontal rule. Mount the machine with all the screws and to ensure the machine is stable. Make sure the system is equipped with a good grounding circuit for prevent electric leakage. And have operation range of ground for skid prevention.

2. Unscrew the nut A on the cabinet body B as shown in **Fig 3**.

Lift the column C; mount it on the machine body B by using the nut A through the bolt located on the machine body B. If the column becomes loose after a period of using, tight them immediately. Otherwise the result of damage to the tyre may happen.

8. Electricity and Pneumatic connections:

Caution: Before installation and connection, check to be sure that the electricity power supply corresponds to the machine technical data. All the installation of electric and pneumatic devices must be operated by a professional electrician.

Connect the compressed air connector which is on the machine right side with compressed air system. The electric grid that the machine connects to must have fuses protection device and good outer cover grounding protection. Install the leakage automatic air switch on the main power supply, leakage current is set at 30A

Caution: No power plug for this machine, the user should self-connect one power plug no less than 16A as well as in line with the machine voltage. Or directly connect with the power supply according to the above requirements.

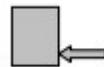


Fig 4

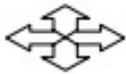
9. Adjusting operation:



Turntable Rotation Pedal (Z)



Bead Breaker Pedal (U)



Jaws open and close Pedal (V)

- 1) Tread the Turntable Rotation Pedal (Z), Turntable (Y) clockwise rotation; Lift up the Turntable Rotation Pedal (Z), Turntable (Y) counterclockwise rotation.
- 2) Tread Bead Breaker Pedal (U), Bead Breaker shovel (F) close toward inside; release Bead Breaker Pedal (U), Bead Breaker shovel (F) return to original position.
- 3) Tread Jaws open and close Pedal (V), four jaws (G) on the turntable open; tread again, four Jaws (G) close. When the pedal is in the middle position, four Jaws stop moving.

Tyre changer operation is consisted of three parts:

- 1) Breaking the tyre bead
- 2) Demounting the tyre
- 3) Mounting the tyre

Caution: Before any operations, don't wear loose clothing and wear protective hat, gloves, and skid-proof shoes. Ensure to exhaust the air in the tyre completely, and remove all the wheel weights from the rim.

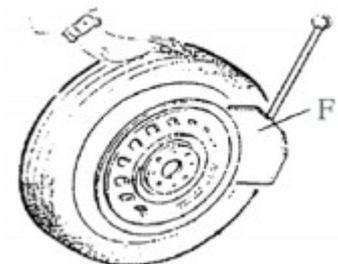


Fig 5

9.1. Breaking the tyre bead:

Ensure to exhaust the air in the tyre completely, place the tyre against the rubber buffer (S). Bring the paddle against the bead about 10mm from the edge of the rim shown as **Fig 5**. Tread Bead breaker Pedal (U) to push paddle into tyre. Repeat the above operations on different positions around the tyre and both sides of tyre until tyre bead is released completely.

9.2. Demounting the tyre :

Ensure to remove all the weights on the wheel rim and to exhaust the air in the tyre completely before this operation. Apply lubricating grease (or similar lubricant) around the tyre bead. Without the lubricant may lead to badly wear and tear on tyre. Clamp the wheel methods shown as below regarded to the ruled dimension:

a- to clamp the wheel from outside:

Tread the Jaws open and close Pedal (V) halfway down to middle, positioning for the four clamps (G) by reference scale on the Turntable (Y); put the tyre on turntable, hold the rim, and tread the Jaws open and close Pedal (V) until the wheel is secured by the jaws.

b- to clamp the wheel from inside:

Positioning for the four clamps (G) and let them all closed. Put the tyre on the turntable and tread the Jaws open and close Pedal (V) to open the clamps thereby lock the wheel in place.

Caution: Check to make sure the wheel firmly secured by the four jaws before next step.

Lower the Vertical Arm (M) until the Mounting/demounting head (I) rests next to the edge of the rim, flip the Locking Handle to lock the Vertical Arm and Swing Arm in position, and also adjust the Rocker Arm make Mounting/demounting head can raise 2mm-3mm automatically from the edge of the wheel rim. Insert the Lifting Lever (T) between the tyre bead and the front section of the mounting/demounting head (I), and move the tyre above the mounting/demounting head as shown as **Fig 6**.

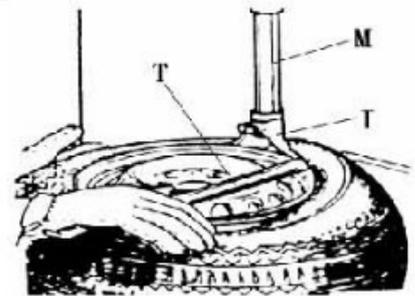


Fig 6

Caution: Chains, bracelets, loose clothes and anything else close to the rotating parts will bring danger to the operator.

With the Lifting Lever held in position, tread the Turntable Rotation Pedal (Z), rotate the Turntable (Y) in a clockwise direction until the tyre is completely separated from the wheel rim.

For the other side tyre demounting, keep using the lifting lever to lift the tyre, make the other side tyre separated from the wheel rim.

9.3. Mounting the tyre :

Caution: Check to make sure that the tyre and the wheel rim are of same size before mounting the tyre.

To avoid any damage on type, lubricate the tyre bead and the wheel rim with the lubrication recommended by manufacturer. Put on the tyre and check the situation.

Caution: When clamp the wheel rim, don't put your hands on the wheel rim to avoid injury during this operation.

Lock the Hexagonal Vertical Mounting Arm, put the tyre on the rim, let the Rocker Arm back to place as demounting the tyre. And let one side of tyre down bead above the rear section of the Mounting/demounting head, the other side under the front section of the Mounting/demounting head. Suppress the tyre with hands or help arm, and then spin the turntable for mounting the tyre down bead.

Repeat the above operation for mounting the tyre up bead. (**Fig 7**)

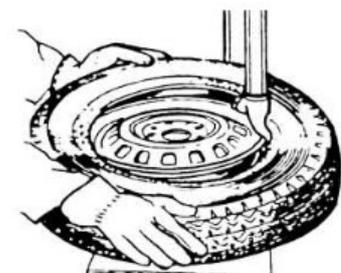


Fig 7

10. Inflating the tire:

Importance: It is very dangerous during inflating operation, take carefully and comply with instruction. When inflating, it will turn to be extremely dangerous if problems happen to tyre or rim. The possible burst force tire goes upward and outward, the big power may cause injury or death of the operator or the people around.

Tyre may burst caused by following:

- 1) The wheel rim and the tyre are not of the same size;
- 2) The tyre or the wheel rim is damaged;
- 3) The pressure of tyre inflation is over the max. pressure recommended by manufacturer;
- 4) The operator fail to comply with the safety regulation;

Please operate as follows:

- 1) Remove the valve cap from the valve stem;
- 2) Check to make sure the air nozzle is pressed down completely over the threads of the valve stem.
- 3) Check to make sure that the tyre and the wheel rim are of the same size;
- 4) Lubricate both the tyre bead and the wheel rim, additional lubrication is required if needed;

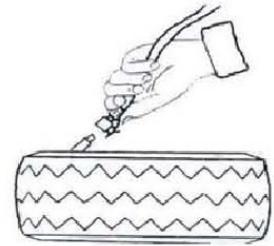


Fig 8

- Fig 8**
- 5) Inflate the tyre with break, while inflating, check the pressure listed on the pressure gauge, also check whether the bead is fixed or not. Repeat operation above until the bead is secured; you need take special steps when inflating convex rim or double convex rim;
 - 6) Continue inflating and check the air pressure frequently until to reach the required pressure.

Note:

Never exceed the max. inflation pressure given by the tyre manufacturer.

Keep hands and your body away from inflating tyres.

Only specially trained persons are allowed to perform the operations, do not allow other to operate or be near the tyre changer.

11. Moving machine:

Please use forklift to move the machine. Disconnect the tyre changer from the electricity power supply and pneumatic power supply, lift the base board and insert the feet of forklift. Then mount the tyre changer machine to a new position and fix it tightly.

Note: the place chosen for fixing the tyre changer must meet the safety regulation.

12. Maintenance:

Caution: only the professional persons can do the maintenance. To prolong the machine's life, maintain the machine timely according to the manual. Otherwise, it will impact the reliability of the machine or even cause injury to operator and others nearby.

Caution: before performing any maintenance, disconnect the tyre changer from the electric power supply and pneumatic power supply, and tread the Jaws open and close Pedal or Turntable Rotation Pedal for 3~4 times to evacuate all compressed air from the machine. Damaged parts must be replaced by professional persons with the spare parts provided by manufacturer.

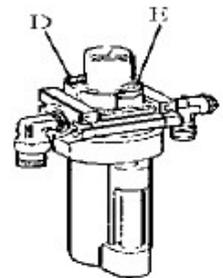


Fig 9

- Clean the machine once every day after work. Clean the dirt on the turntable with diesel oil once per week and lubricate the slides and clamps.

- Following maintenance must be done at least once per month:

Check oil level in Oil Fog Maker, please be filled with SAE30# oil if need.

Unscrew with hex wrench (E). Based on connection of compressed air, first to

tread Jaws open and close Pedal or Turntable Rotation Pedal 5-6 times, and

then check whether oil in Oil Fog Maker drops down a drip of oil. For

continuous operation, tread twice every time, drop down a drip of oil,

otherwise adjust the screw (D) that controlled oil enter with minus screwdriver.

(Fig 9)

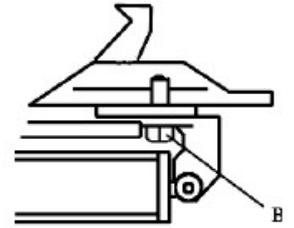


Fig 10

Note: After the first 20 days of use, retighten the jaws with tightening screws (B) on the Turntable (Fig 10)

Note: in the event of turntable lose power, check to see if the belt is tight as follow steps:

Remove the left side cover by unscrewing the screws; adjust two screws located on the motor support, keep a suitable distance between motor support and motor base; tight the screws for the belt tension.(Fig 11)

Caution: please disconnect the machine from electric power supply and pneumatic power supply.

Note: If Hexagonal Vertical Arm not be locked or not meet the requirement that 2-3mm from the bottom of Mounting/demounting head to rim, please adjust Hexagonal Locking Plate, refer to Fig 12 and adjust the (X).

Note: In order to achieve the reliability of jaws and Bead Breaker shovel, operate as follows to keep their valves clean:

1. Remove the left side cover of the machine body by unscrewing the two screws;
2. Loosen the valve Muffler (A) which belong to Jaws open and close Pedal and Bead Breaker Pedal; (Fig 13)
3. Clean the silencers with compressed air, please replace it referring to the spare parts list if it is damaged. (Fig 13)

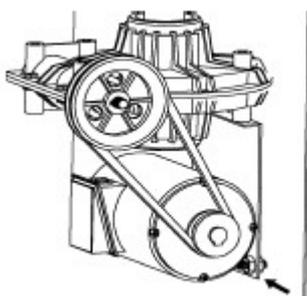


Fig 11

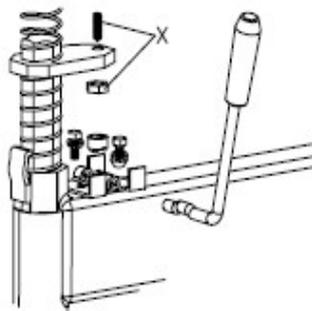


Fig 12

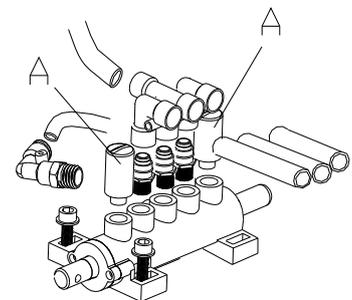
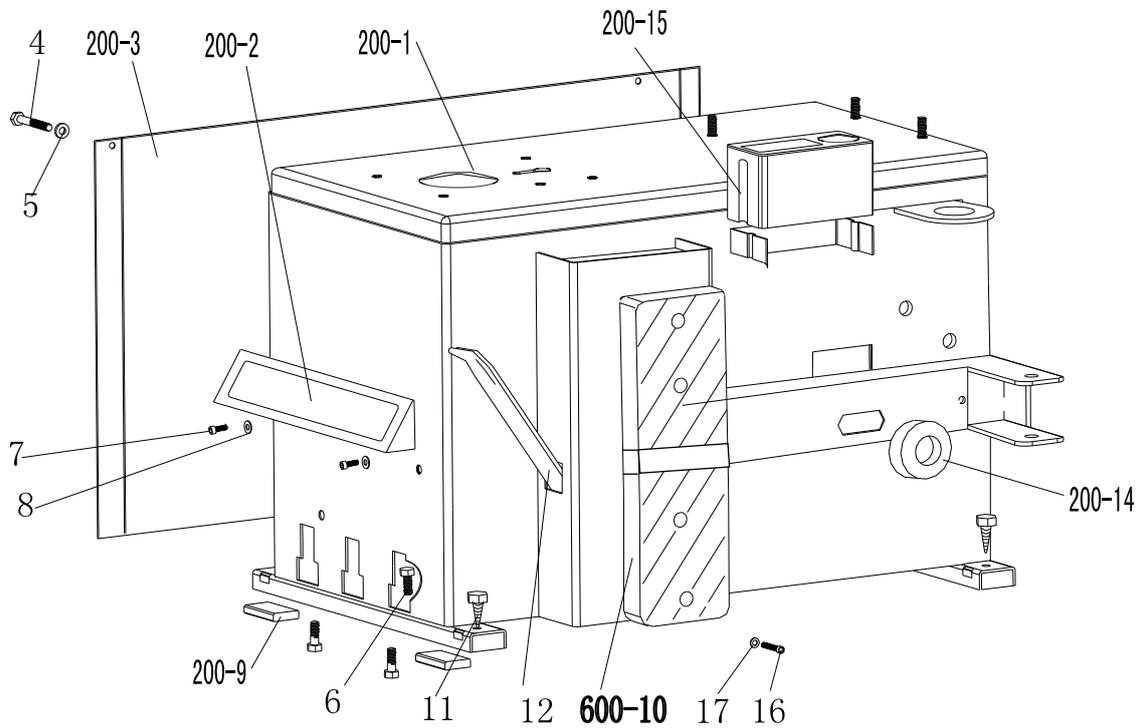


Fig 13

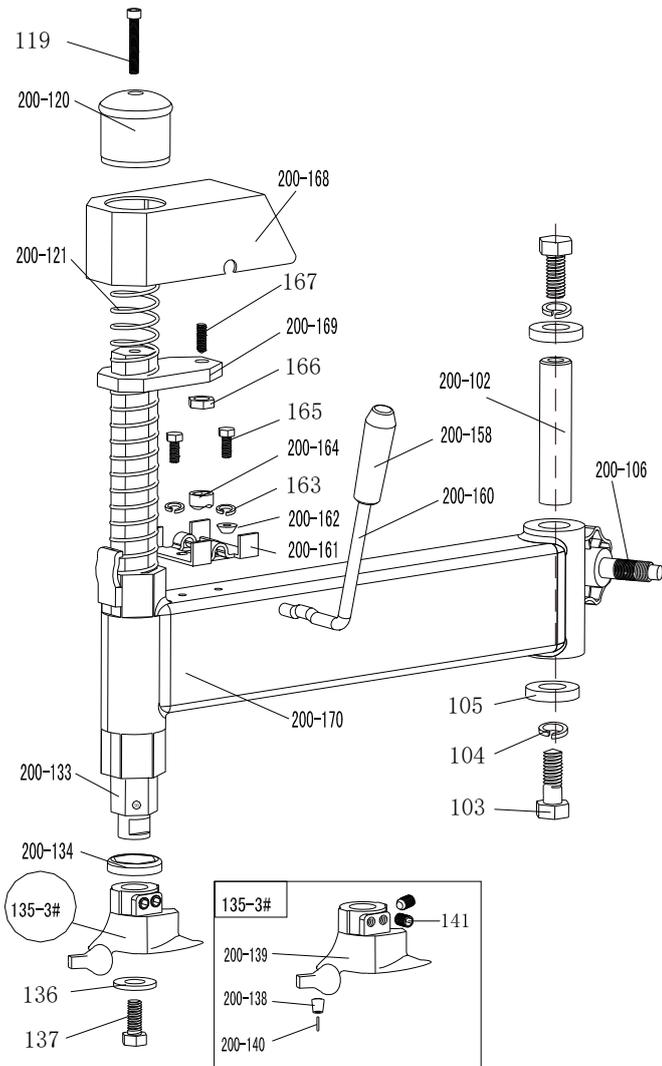
13. Trouble shooting table:

| Problem | Reason | Solution |
|--|--|--|
| The turntable rotate just in one direction or can't rotate. | Reverse Switch broken | Replace the Reverse Switch |
| | Belt broken | Replace the belt |
| | The Motor's malfunction | Check the motor cable or terminal block wire; Replace the motor if it was broken. |
| Demount or fix the wheel, the turntable can't lock (spin with wheel); The jaws delay to open/close; The turntable locks the rim incorrectly. | Leakage of Air network | Check all the parts on the air network. |
| | The clamping cylinder can't work. | Replace the cylinder piston. |
| | Worn jaws | Replace the jaws. |
| | Broken washers of the chuck cylinder | Replace it. |
| The mounting/demounting head always touch the rim during operation. | The locking plate incorrectly adjust or unqualified. | Replace or adjust it. |
| | Screws on the chuck loose; the Hexagonal Vertical Arm can't be locked by Locking Plate | Tighten the screws; replace the Locking Plate. |
| The Bead Breaker Pedal and Jaw open and close Pedal can't turn back to the original position. | pedal spring broken | Replace it. |
| The Bead Breaker shovel operates difficultly. | Jammed silencer | Clean it or replace it. |
| | The washer on the Bead Breaker cylinder is broken. | Replace it. |

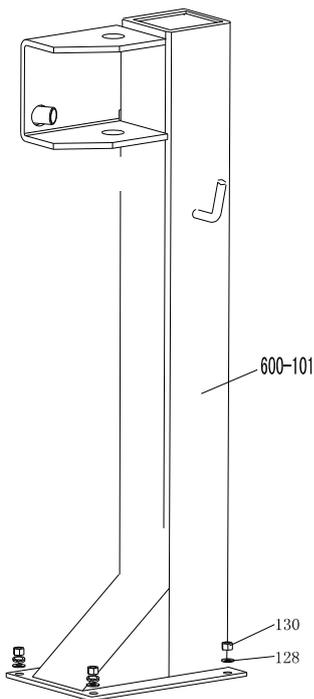
14. Exploded drawing:

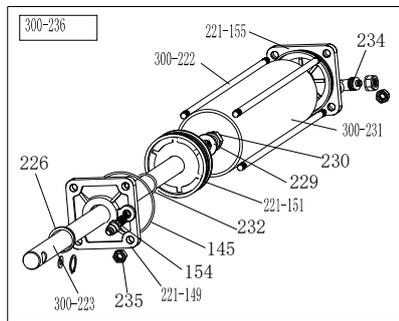
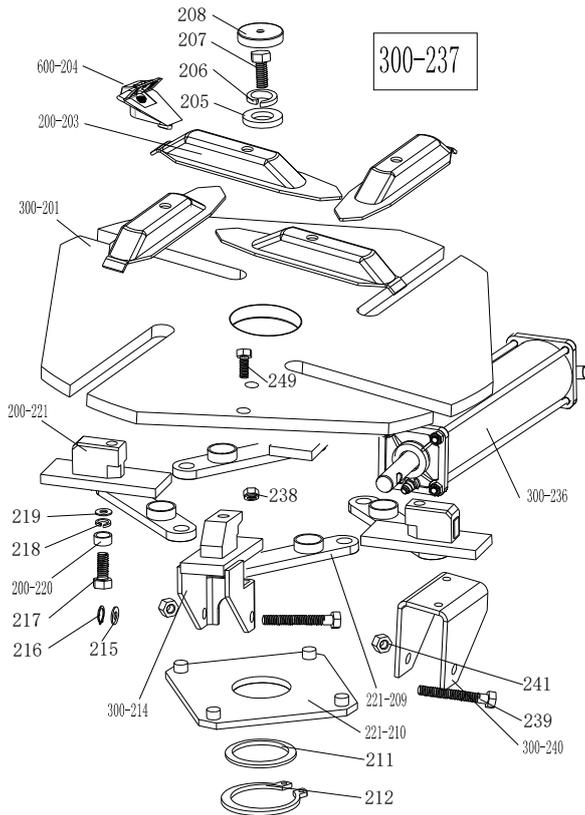


| | | |
|--------|-----------------|----------------------------|
| 200-1 | CX-200-010000-0 | Machine body |
| 200-2 | CZ-200-080000-0 | Pedal front cover |
| 200-3 | CX-200-020000-0 | Left cover |
| 4 | B-010-060101-0 | Hex socket head bolt M6×10 |
| 5 | B-040-061412-1 | Flat washer Ø6*14*1.2 |
| 6 | B-014-080251-0 | Outer hex bolt M8x25 |
| 7 | B-010-080201-0 | Hex socket head bolt M8×20 |
| 8 | B-040-061412-1 | Flat washer Ø 6*14*1.2 |
| 200-9 | C-000-001020-0 | Rubber foot buffer |
| 600-10 | C-600-500000-0 | Bead breaker buffer |
| 11 | B-027-060401-0 | Grounding screw M6x40 |
| 12 | C-200-580000-0 | Lifting lever |
| 200-13 | C-200-360000-0 | Ripping bar |
| 200-14 | C-200-510000-0 | Bead breaker arm rubber |
| 200-15 | C-200-470000-0 | Oil-water box |
| 16 | B-010-080201-0 | Hex socket head bolt M8x20 |
| 17 | B-040-081715-1 | Flat washer Ø 8*17*1.5 |

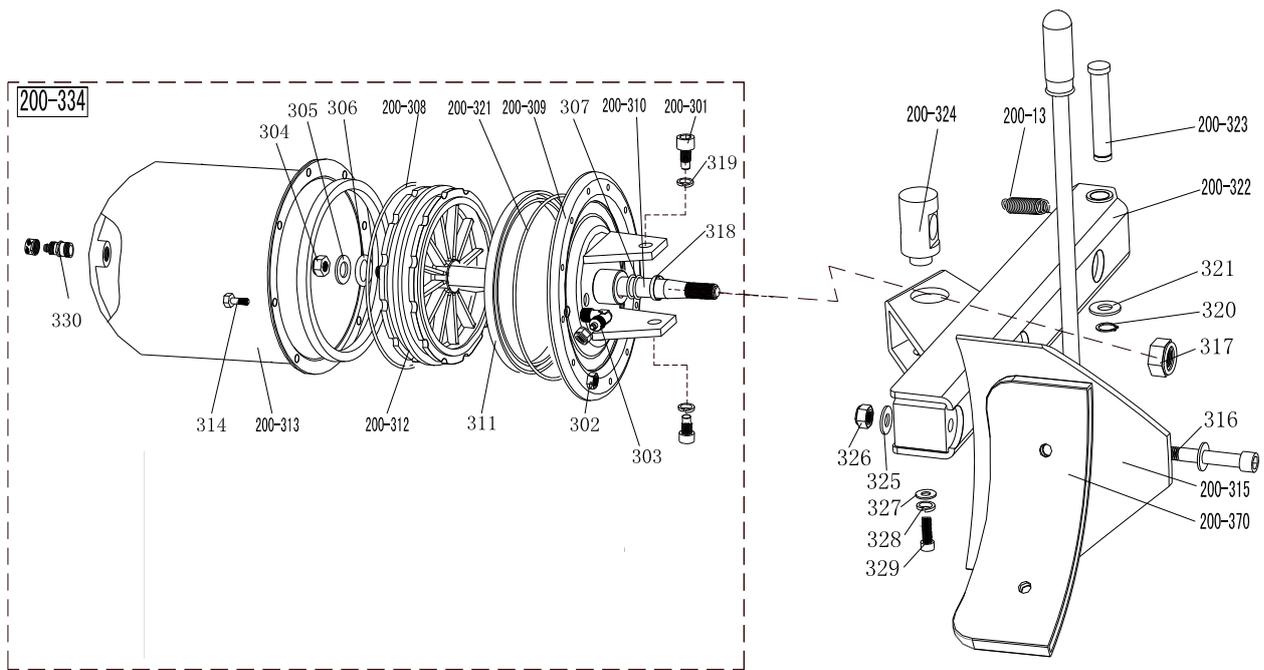


| | | |
|---------|-----------------|--------------------------------|
| 600-101 | CX-204-250000-0 | Square column |
| 200-102 | CX-200-190000-0 | Swing arm pin |
| 103 | B-014-140301-0 | Outer hex bolt M14x30 |
| 104 | B-050-140000-0 | Spring washer Ø14 |
| 105 | CX-200-140000-0 | Big washer |
| 200-106 | C-200-350000-0 | Column adjust handle |
| 119 | B-010-100501-0 | Hex socket head bolt M10×50 |
| 200-120 | C-200-490000-0 | Vertical arm cap 200 |
| 200-121 | C-200-390000-0 | Vertical arm spring |
| 128 | B-040-102020-1 | Flat washer Ø10X2 |
| 130 | B-001-100001-0 | Self-locking nut M10 |
| 200-133 | CX-200-160000-0 | Vertical arm 200 |
| 200-134 | C-200-520000-0 | Vertical arm washer |
| 136 | CX-200-170000-0 | Mount/demount head flat washer |
| 137 | B-014-100251-0 | Outer hex bolt M10×25 |
| 135-3# | CW-113-020003-0 | Complete mount/demount head3# |
| 200-138 | CX-200-150200-0 | Mount/demount head pulley |
| 200-139 | C-200-150100-3 | Mount/demount head 3# |
| 200-140 | C-200-150400-0 | Hex round pin |
| 141 | B-007-120161-0 | Hex socket head bolt M12X16 |
| 200-158 | C-200-230200-0 | Locking Handle cover |
| 200-160 | CX-200-230000-0 | Locking Handle |
| 200-161 | CX-200-200000-0 | Locking plate |
| 200-162 | C-200-240000-0 | Locking block cover |
| 163 | B-050-080000-0 | Spring washer Ø8 |
| 200-164 | C-200-210000-0 | Eccentric shaft nut |
| 165 | B-014-080251-0 | Outer hex bolt M8×25 |
| 166 | B-004-120071-1 | Nut M12X1.75X7 |
| 167 | B-007-120301-0 | Hex socket head bolt M12X30 |
| 200-168 | C-200-480000-0 | Locking plate cap |
| 200-169 | CX-200-220000-0 | Hex locking board 200 |
| 200-170 | CX-200-180000-0 | Swing arm 470 |



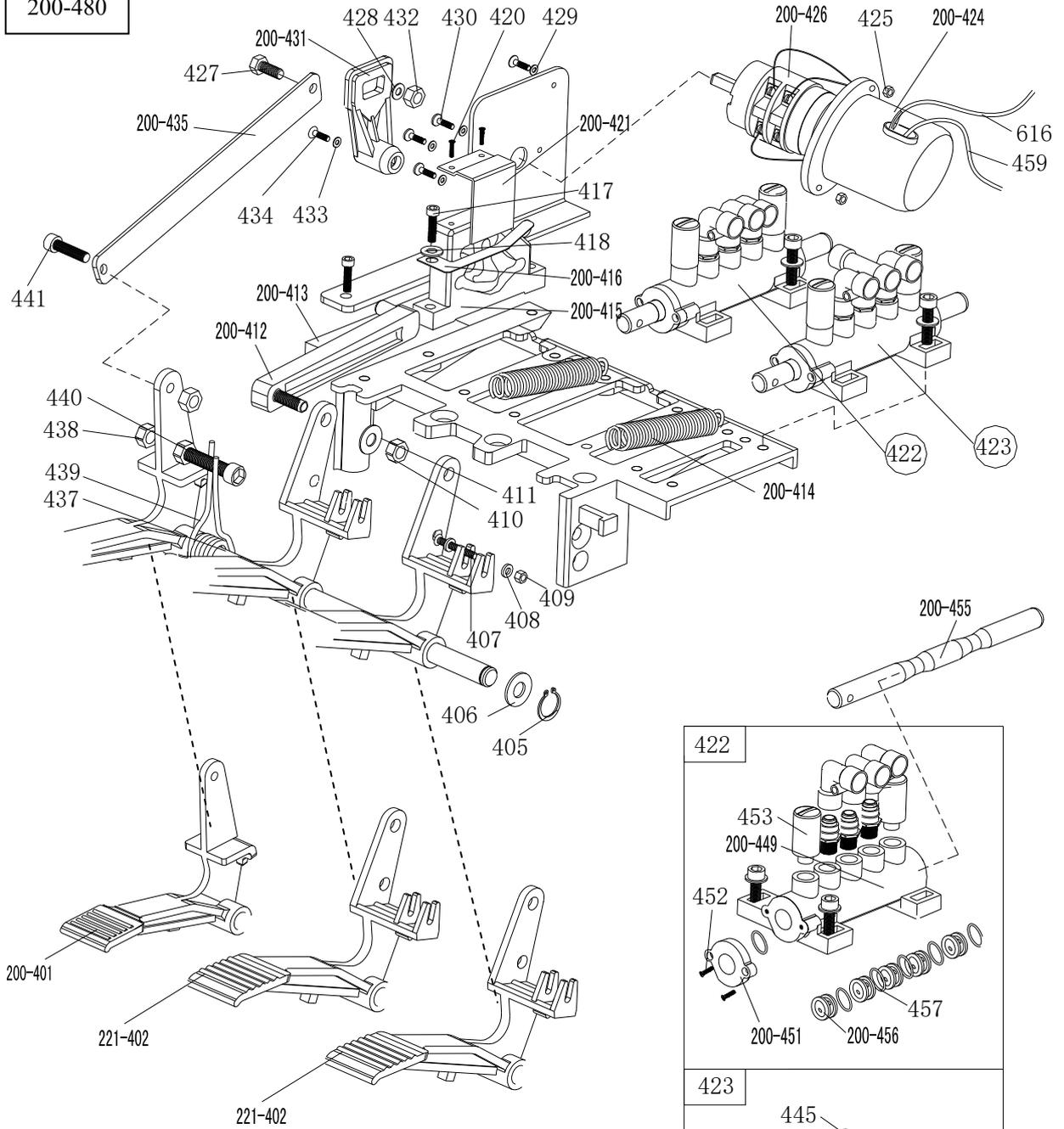


| | | |
|---------|-----------------|---------------------------------------|
| 300-201 | CX-300-130000-0 | Non-central Turntable assembly |
| 200-203 | CX-200-120000-0 | Jaw cap 200 |
| 600-204 | C-600-570000-0 | Jaw 600 |
| 205 | CX-200-140000-0 | Big washer |
| 206 | B-050-160000-0 | Spring washer Ø16 |
| 207 | B-014-160401-0 | Outer hex bolt M16×40 |
| 208 | C-200-440000-0 | Turntable cap |
| 221-209 | CX-221-310000-0 | Connection rod assembly 615 |
| 221-210 | CX-221-280000-0 | Square turntable 615 |
| 211 | CX-200-290000-0 | Square turntable washer |
| 212 | B-055-650001-0 | Snap ring Ø65(shaft) |
| 300-214 | CX-300-011100-0 | Jaw seat assembly |
| 215 | B-040-122520-1 | Flat washer Ø12X25X2 |
| 216 | B-055-120001-0 | Snap ring Ø12(shaft) |
| 217 | B-014-120801-0 | Outer hex bolt M12×80 |
| 218 | B-046-122050-1 | Teeth locking washer Ø12x20.5x1 |
| 219 | B-040-123030-1 | Flat washer Ø12X30X3 |
| 200-220 | CX-200-300000-0 | Connection rod nut |
| 200-221 | CX-200-110100-0 | Jaw slide guide without pin |
| 600-222 | C-600-100400-0 | Threaded connection rod |
| 600-223 | C-600-100200-0 | Clamping cylinder piston rod |
| 221-149 | C-221-350100-0 | Tilting cylinder cover without handle |
| 154 | S-011-010808-0 | Straight union 1/8"-Ø8 |
| 226 | S-005-020075-0 | V- seal 20*28*7.5 |
| 145 | S-000-068353-0 | O-seal 68.26*3.53 |
| 221-151 | C-221-550000-0 | Tilting cylinder piston |
| 229 | B-040-122520-1 | Flat washer Ø12X25X2 |
| 230 | B-004-120071-1 | Nut M12X7X1.75 |
| 300-231 | C-300-100500-0 | Clamping cylinder barrel |
| 232 | S-000-019262-0 | O-seal 19.6X2.62 |
| 221-155 | C-221-350300-0 | Tilting cylinder cover with handle |
| 234 | S-018-010808-0 | Union 1/8 |
| 235 | B-001-080001-0 | Self-locking nut M8 |
| 300-236 | CA-005-030000-S | Complete clamping cylinder L223 |
| 300-237 | CA-004-030000-0 | Complete Non-central Turntable |
| 249 | B-010-080251-0 | Hex socket head bolt M8×25 |
| 238 | B-001-120001-0 | Self-locking nut M12 |
| 239 | B-014-120801-0 | Hex socket head bolt M12X80 |
| 300-240 | CX-300-110400-0 | Jaw plate support2 |
| 241 | B-001-120001-0 | Self-locking nutM12 |



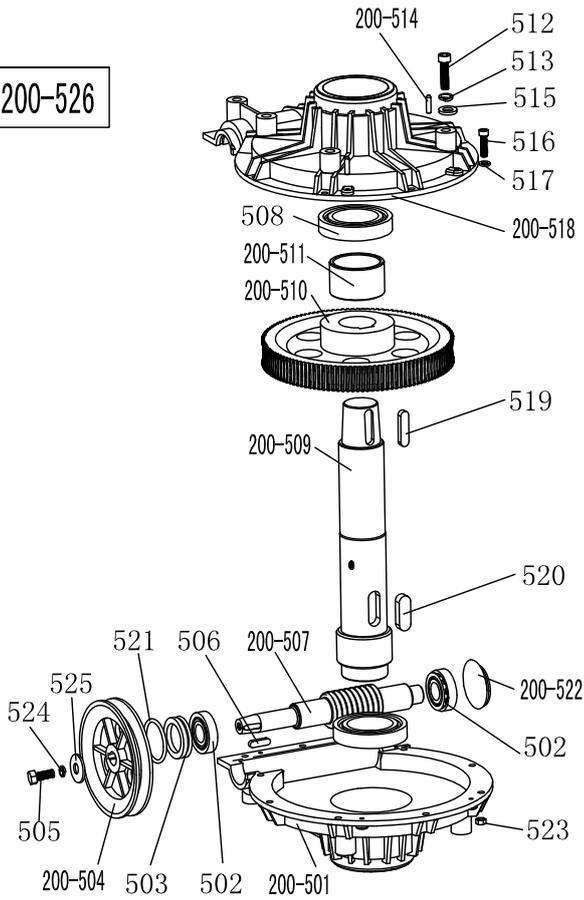
| | | | | | |
|---------|-----------------|--------------------------------------|---------|-----------------|--|
| 200-13 | C-200-360000-0 | Bead breaker arm spring | 317 | B-004-160001-1 | Self-locking nut M16*1.5 |
| 200-301 | B-010-140301-0 | Hex socket head bolt M14×30 | 318 | U-006-000001-2 | Guide belt |
| 302 | B-001-060001-0 | Self-locking nut M6 | 200-370 | C-200-070600-0 | Bead breaker shovel protection cover(optional) |
| 303 | S-018-010408-0 | Union (90°)1/4-Ø8 | 319 | B-050-140000-0 | Spring washer Ø14 |
| 304 | B-004-160001-1 | Nut M16*1.5 | 320 | B-055-160001-0 | Snap ring Ø16 |
| 305 | B-040-162820-1 | Flat washer Ø16*28*2 | 321 | | Flat washer |
| 306 | S-000-016265-0 | O-seal Ø 16*2.65 | 200-321 | S-000-175500-0 | O-seal Ø173.4x5.3 |
| 307 | S-000-020265-0 | O-seal Ø 20*2.65 | 200-322 | CX-200-030000-0 | Bead breaker arm 200 |
| 200-308 | S-000-180500-0 | O-seal 180x5 | 200-323 | CX-200-040000-0 | Bead breaker pin |
| 200-309 | CX-200-050500-0 | Bead breaker cylinder cover assembly | 200-324 | CX-200-050600-0 | Bead breaker cylinder rotating pin |
| 200-310 | C-200-050100-0 | Bead breaker cylinder piston rod | 325 | B-040-122520-1 | Flat washer Ø12*24*2 |
| 311 | S-005-168115-0 | V-seal 185X168X11.5 | 326 | B-001-120001-0 | Self-locking M12 |
| 200-312 | C-200-050200-0 | Bead breaker cylinder piston | 327 | B-040-083030-1 | Flat washer Ø8*30*3 |
| 200-313 | CX-200-050300-0 | Bead breaker cylinder barrel | 328 | B-050-080000-0 | Spring washer Ø8 |
| 314 | B-010-060161-0 | Hex socket head bolt M6×16 | 329 | B-014-080201-0 | Outer hex bolt M8×20 |
| 200-315 | CX-200-070000-0 | Bead breaker shovel assembly | 330 | S-011-010808-0 | Straight union 1/8-Ø8 |
| 316 | B-010-120901-0 | Hex socket head bolt M12×90 | 200-334 | CW-108-020000-0 | Complete bead breaker cylinder |

200-480

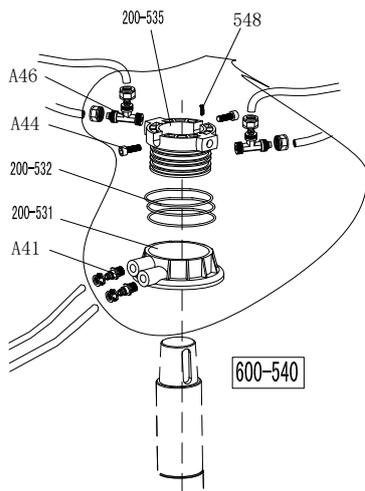


| | | | | | |
|---------|-----------------|--|---------|-----------------|--------------------------------|
| 200-401 | C-200-060400-0 | Reverse switch pedal | 428 | B-040-061210-1 | Flat washer Ø 6X12X1 |
| 221-402 | C-221-060300-0 | 5-way valve pedal (right) | 429 | B-040-040000-1 | Flat washer Ø 4 |
| 405 | B-055-120001-0 | Snap ring Ø12 | 430 | B-024-040161-0 | Cross-round head screw M4*16 |
| 406 | B-040-122520-1 | Flat washer Ø12*24*2 | 200-431 | C-200-530000-0 | Reverse switch handle |
| 407 | B-024-040301-0 | Cross head screw M4X30 | 432 | B-001-060001-0 | Self-locking nut M6 |
| 408 | B-040-040000-1 | Flat washer Ø 4 | 433 | B-040-030000-1 | Flat washer Ø3 |
| 409 | B-001-040001-0 | Self-locking nut M4 | 434 | B-017-030161-0 | Cross head screw M3X18 |
| 410 | B-001-080001-0 | Self-locking nut M8 | 200-435 | CX-200-060600-0 | Pedal connection rod |
| 411 | B-040-081715-1 | Flat washer Ø8*17*1.5 | 437 | CX-200-060700-0 | Pedal front shaft |
| 200-412 | C-200-061300-0 | Cam connection rod | 438 | B-004-080001-0 | Nut M8 |
| 200-413 | C-200-060100-0 | Pedal support board | 439 | C-200-370000-0 | Pedal twist spring |
| 200-414 | C-200-380000-0 | Pedal Spring | 440 | B-010-080501-0 | Hex socket head bolt M8x50 |
| 200-415 | C-200-061500-0 | Cam | 441 | B-010-080201-0 | Hex socket head bolt M8x20 |
| 200-416 | C-200-810000-0 | Cam washer | 442 | S-012-010808-0 | Union 1/8- Ø 8 |
| 417 | B-010-060201-0 | Hex socket head bolt M6x20 | 445 | S-016-010808-2 | T-union1/8-2* Ø 8 |
| 418 | B-040-061210-1 | Flat washer Ø6*12*1 | 200-449 | C-200-060901-0 | 5-way valve (left) |
| 420 | B-019-290121-0 | Cross head self tapping screw | 200-451 | C-200-061100-0 | 5-way valve cover |
| 200-421 | CX-200-060500-0 | Cam cover | 452 | B-024-290121-0 | cross head screw ST2.9*14 |
| 422 | CW-110-020000-0 | Complete 5-way valve for clamping cylinder | 453 | S-023-010801-0 | Muffler 1/8" |
| 423 | CW-110-020001-0 | Complete 5-way valve for bead breaker cylinder | 200-455 | CX-200-061200-0 | 5-way valve rod |
| 200-424 | C-200-061400-0 | Reverse switch cover | 200-456 | C-200-061000-0 | 5-way valver rod spacer |
| 425 | B-004-040001-0 | Nut M4 | 457 | S-000-012400-0 | O-seal 12*20*4 |
| 200-426 | S-060-016000-1 | Reverse switch | 459 | C2-000-103150-0 | Power supplier cable |
| 427 | B-010-060201-0 | Hex socket head bolt M6x20 | 616 | C2-000-205150-0 | Motor cable |
| | | | 200-480 | CW-109-020000-0 | Complete 3-pedals assembly 200 |

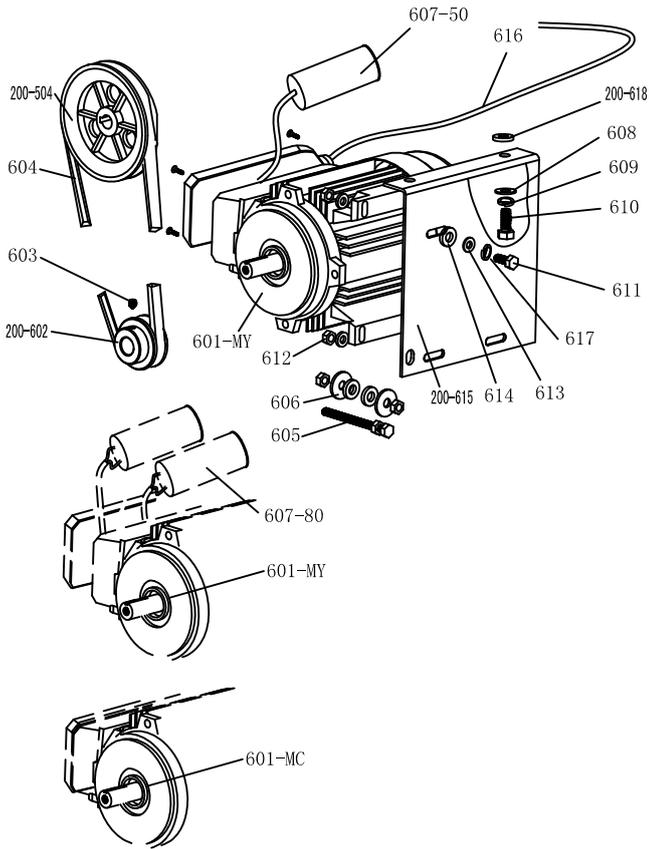
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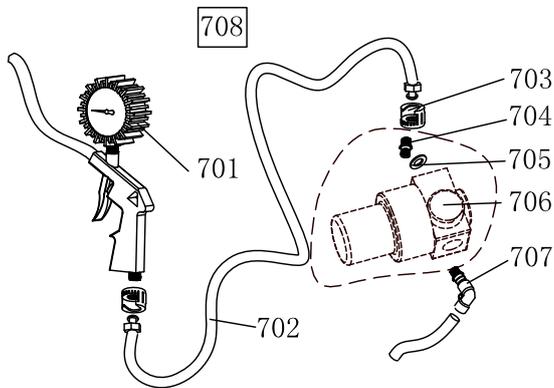
| | | |
|---------|-----------------|--|
| 200-501 | C-300-320302-0 | Gear box lower cover |
| 502 | S-040-030204-0 | Bearing 30204 |
| 503 | S-005-020080-1 | Gear box seal $\phi 20 \times 35 \times 8$ |
| 200-504 | C-200-320500-0 | Gear Belt pulley |
| 505 | B-014-080251-0 | Outer hex bolt M8×25 |
| 506 | B-065-006020-0 | Key washer 6×20 |
| 200-507 | C-200-320400-0 | Worm rod |
| 508 | S-040-006010-0 | Bearing 6010 |
| 200-509 | C-200-320200-0 | Worm gear shaft |
| 200-510 | C-200-320100-0 | Worm gear |
| 200-511 | CZ-200-320600-0 | Worm gear shaft spacer |
| 512 | B-014-100551-0 | Outer hex bolt M10×55 |
| 513 | B-050-100000-0 | Spring washer $\phi 10$ |
| 200-514 | B-060-006020-0 | Pin 6X20 |
| 515 | B-040-102020-1 | Flat washer $\phi 10 \times 20 \times 2$ |
| 516 | B-010-060201-0 | Hex socket head bolt M6×20 |
| 517 | B-040-061412-1 | Flat washer $\phi 6 \times 14 \times 1.2$ |
| 200-518 | C-300-320301-0 | Gear box upper cover |
| 519 | B-065-010040-0 | Key washer 10×40 |
| 520 | B-065-014040-0 | Key washer 14×40 |
| 521 | S-000-030355-0 | O-seal $\phi 30 \times 3.55$ |
| 200-522 | C-200-320700-0 | Oil resistant seal |
| 523 | B-001-060001-0 | Self-locking nut M6 |
| 524 | B-050-080000-0 | Spring washer $\phi 8$ |
| 525 | B-040-083030-1 | Flat washer $\phi 8 \times 30 \times 3$ |
| 200-526 | CW-107-020001-0 | Complete gear box |



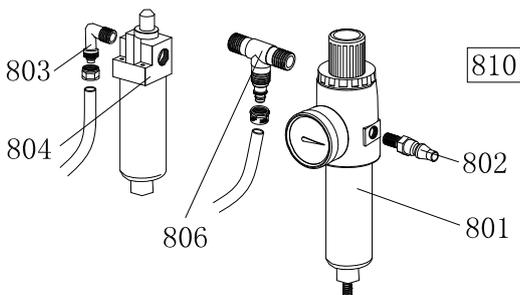
| | | |
|---------|-----------------|------------------------------|
| A04 | S-015-000008-3 | T-union 3* $\phi 8$ |
| A44 | B-010-060161-0 | Hex socket head bolt M6×16 |
| A46 | S-015-010808-2 | T-union 1/8-2* $\phi 8$ |
| 200-531 | CZ-200-430100-0 | Rotating valve casing |
| 200-532 | S-000-059262-0 | O-seal 59.9X2.62 |
| 200-535 | CZ-200-430200-0 | Rotating valve mandrel |
| A41 | S-011-010808-0 | Straight union 1/8- $\phi 8$ |
| 548 | B-007-040061-0 | Hex socket head bolt M4X6 |
| 600-540 | CW-006-060000-0 | Complete Rotating valve |



| | | |
|---------|-----------------|----------------------------|
| 200-504 | C-200-320500-0 | Gear Belt pulley |
| 601-MC | S-050-220110-5 | Motor 220V/50HZ |
| 601-MY | S-050-230075-0 | Motor 220v |
| 200-602 | CX-200-330000-0 | Motor Belt pulley |
| 603 | B-007-080121-0 | Hex socket head bolt M8×12 |
| 604 | S-042-000686-0 | Tyre changer belt A-28 |
| 605 | B-014-080651-0 | Outer hex bolt M8X65 |
| 606 | B-040-083030-1 | Flat washer Ø8X30X3 |
| 607-80 | S-063-008000-0 | Capacitor 80µf,110V |
| 607-50 | S-063-005000-0 | Capacitor 50µf,220V |
| 608 | B-040-102020-1 | Flat washer Ø10X20X2 |
| 609 | B-050-100000-0 | Spring washer Ø10 |
| 610 | B-014-100251-0 | Outer hex bolt M10X25 |
| 611 | B-014-080351-0 | Outer hex bolt M8X35 |
| 612 | B-004-080001-0 | Nut M8 |
| 613 | B-040-082220-1 | Flat washer φ8X22X2 |
| 614 | C-200-560000-0 | Motor rubber washer |
| 200-615 | CX-200-340000-2 | Motor support |
| 616 | CZ-000-205150-0 | Motor cable 5×1.0 |
| 617 | B-050-080000-0 | Spring washer φ8 |
| 200-618 | C-200-560000-0 | Motor rubber buffer |

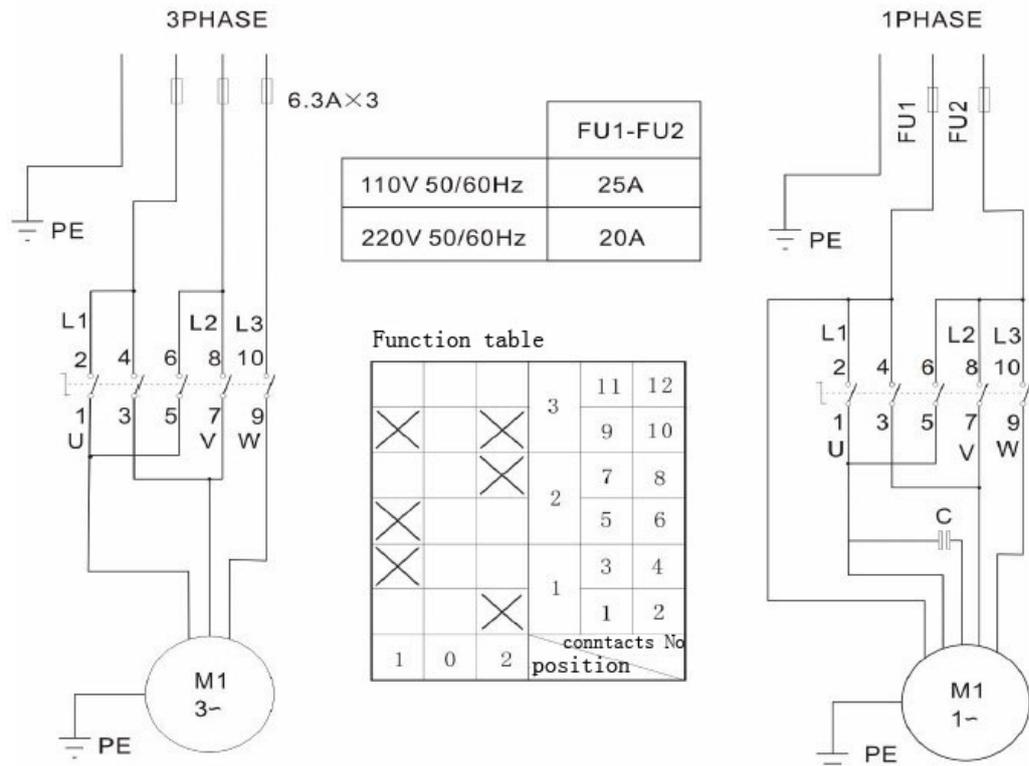


| | | |
|-----|-----------------|---------------------------------|
| 701 | S-038-000100-0 | Inflating gun indicator |
| 702 | CX-001-000002-0 | Rubber connection hose |
| 703 | S-025-104008-0 | Notch nut |
| 704 | S-011-010414-1 | Straight union 1/4-1/4 |
| 705 | B-040-132420-1 | Flat washer Ø13 |
| 706 | S-030-010400-2 | Pressure adjust valve(optional) |
| 707 | S-012-010408-0 | Quick union 1/4-Ø8 |
| 708 | CW-090-000201-0 | Complete inflating gun |

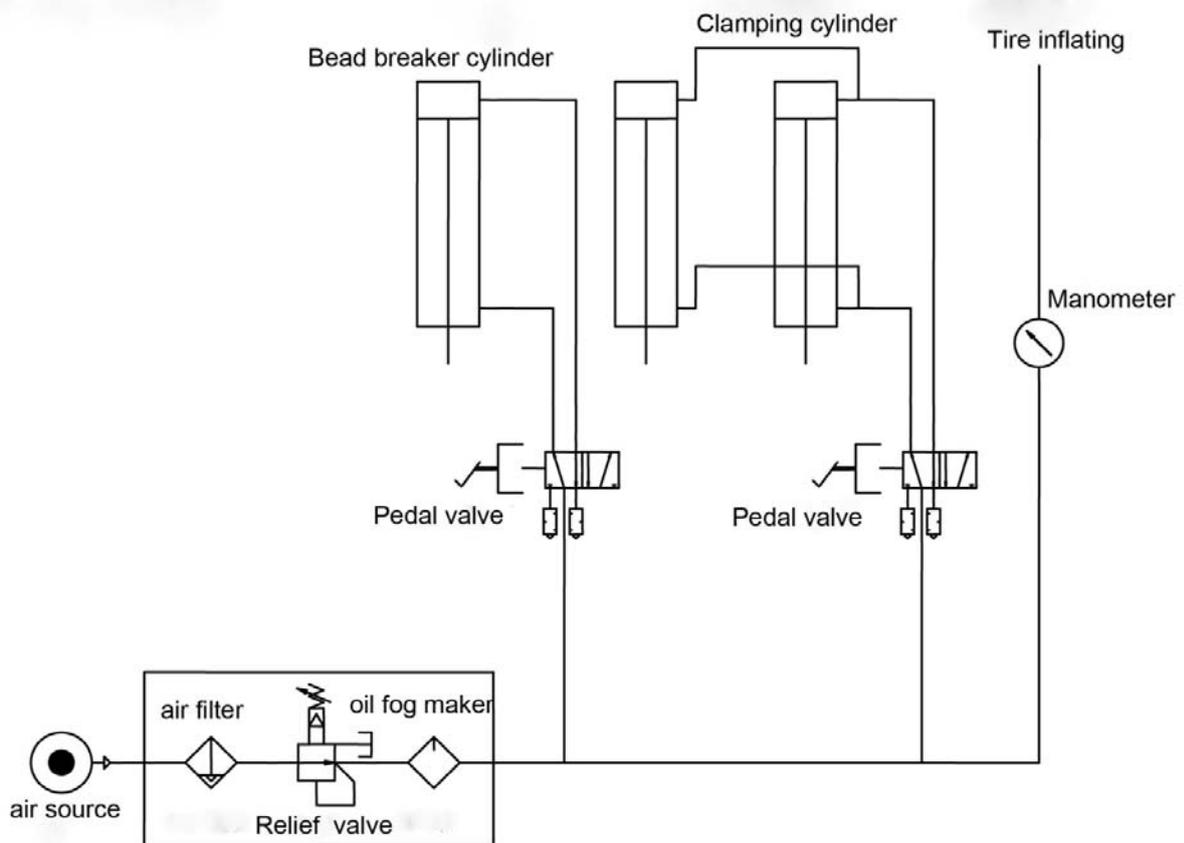


| | | |
|-----|-----------------|------------------------|
| 801 | S-033-200002-1 | Relief pressure filter |
| 802 | S-025-000050-0 | Quick nozzle |
| 803 | S-018-010408-0 | Union (90°) |
| 804 | S-033-200002-2 | Oil fog maker |
| 806 | S-015-010408-2 | T-union 2X1/4-φ8 |
| 810 | CW-114-020005-0 | Complete oil fog maker |

15. Circuit diagram:



16. Pneumatic drawing:



WHEEL BALANCING MACHINE INSTRUCTION MANUAL INDEX

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1. Introduction

An imbalanced wheel will make the wheel jump and steering wheel wobble while driving. It can baffle the driver to drive, aggrandize the cleft of combine area of steering system, damage the vibration damper and steering parts, and increase the probability of the traffic accidents. A balanced wheel will avoid all these problems.

This equipment adopts the new LSI (Large Scale Integrated circuit) to constitute the hardware system that acquires processes and calculates information at a high speed.

Read the manual carefully before operating the equipment to ensure normal and safe operation. Dismantling or replacing the parts of equipment should be avoided. When it needs repairing, please contact with technique service department. Before balancing, ensure the wheel fixed on the flange tightly. Operator should wear close-fitting smock to prevent from hanging up. Non-operator does not start the equipment.

No use while beyond the stated function range of manual

2. Specification and Features

2.1 Specification

- Max wheel weight: 65kg
- Power supply: DC12V 1A
- Rotating speed: about 120r/min
- Cycle time: 8s
- Rim diameter: 10 " ~24 " (256mm~610mm)
- Rim width: 1.5 " ~20 " (40mm~510mm)
- Noise: <70dB
- Net weight: 30Kg
- Dimensions:

2.2 Features

- Adopt 6 LED display, it has flexible interface operating function;
- Energy saving, motor free, hand spin;
- Various balancing modes can carry out counterweights to stick, clamp, or hidden stick etc;
- Intelligent self-calibrating;
- Automatic self error diagnosis and protection function;
- Applicable for various rims of steel structure and aluminum alloy structure;

2.3 Working Environment

- Temperature: 5~50°C ;
- Altitude ≤4000m;
- Humidity: ≤85%

3. The Structure of Dynamic Balancer

Dynamic balancer consists of mechanical section and electrical section:

3.1 Mechanical section

Mechanical section consists of support bracket and rotary main shaft; they are together fixed on the frame.

3.2 Electrical system

- (1) The microcomputer system consists of the LSI, new high speed Micro CPU, LED display and keyboard.
- (2) Speed testing and positioning system consists of gear and opto-electronic coupler.

(3) Horizontal and vertical pressure sensor

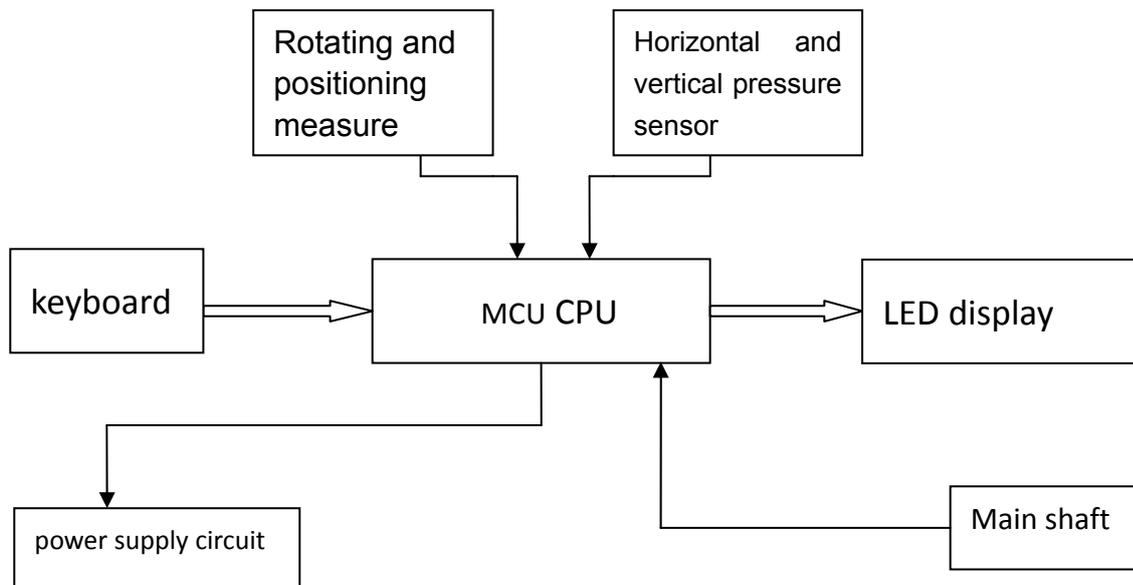


Fig 3-1 Electric system figure

4. Installation of Dynamic Balancer

4.1 Opening and Checking

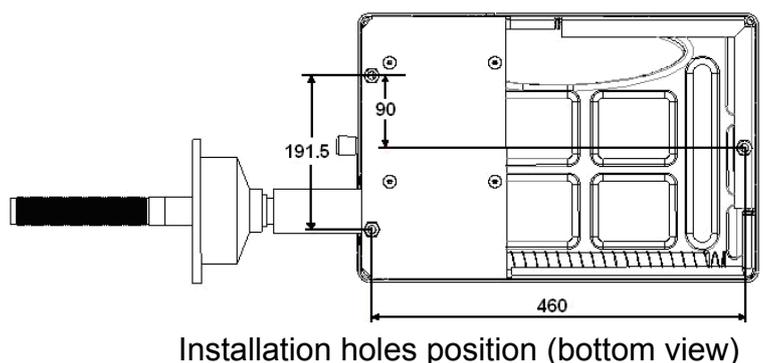
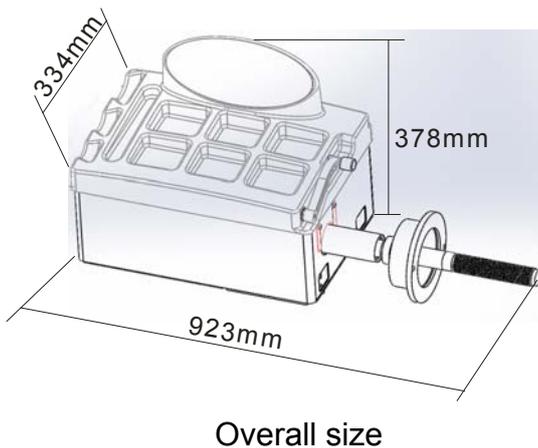
Open the package and check whether there are damaged parts. If there are some problems, please do not use the equipment and contact with the supplier. Standard accessories with equipment are shown as follow:

| | |
|--------------------------|---|
| Screw stud of drive axis | 1 |
| Balancing pliers | 1 |
| Allen wrench | 1 |
| Measure caliper | 1 |
| Quick release nut | 1 |
| Cone | 3 |
| Counterweight (100g) | 1 |

4.2 Installing machine

4.2.1 The balancer must be installed on firm platform which is more than 60CM high and fixed with 3pcs M8 screws

4.2.2 There should be 500mm around the balancer in order to operate conveniently



4.3 Installing screw rod

Install screw rod on the main axis with M10 × 150 socket bolt, then fasten the bolt.
(Refer to Fig 4-1)



Fig 4-1

5. LED display control panel and function keys

5.1 Introduction of display control panel

Fig 5-1 is figure of keyboard and display, introduction is as follows:

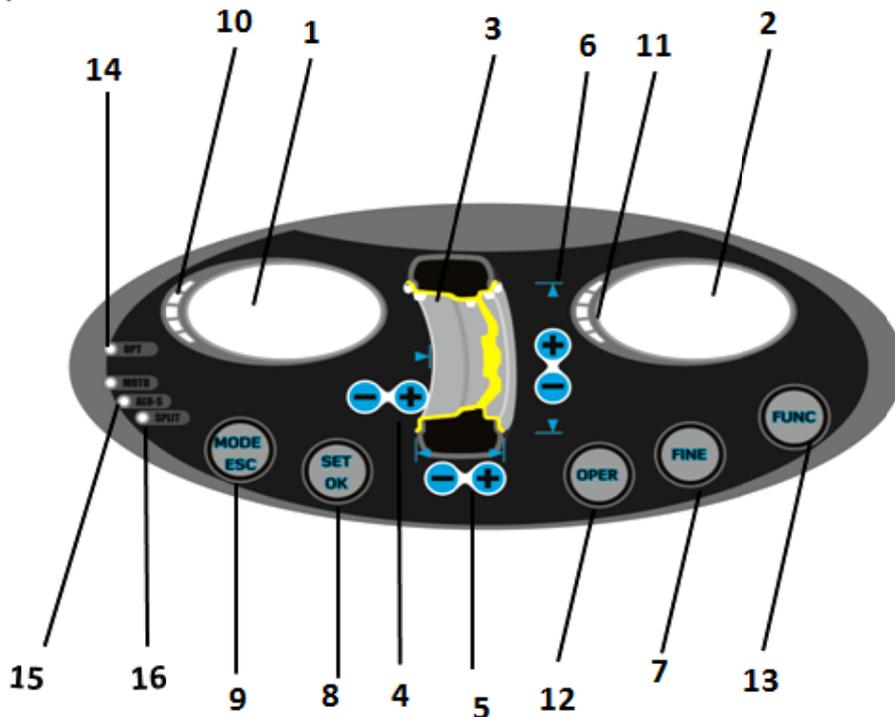


Fig 5-1

- 1- Digital readout, amount of imbalance, inside
- 2- Digital readout, amount of imbalance, outside
- 3- Balancing mode
- 4- Push buttons, manual DISTANCE setting
- 5- Push buttons, manual WIDTH setting
- 6- Push buttons, manual DIAMETER setting
- 7- Show real imbalance amount (less than 5gram), function key ①gram/ounce ②mm/inch ③self-calibration
- 8- Push button, re-calculation
- 9- Function key of selecting balancing mode
- 10- Show imbalance position of outside
- 11- Show imbalance position of inside

- 12- Push button, optimization of unbalance
- 13- Split function
- 14- Indication of optimization
- 15- Indication of ALU-S mode
- 16- Indication of split

NOTE: Only use the fingers to press push buttons. Never use the counterweight pincers or other pointed objects.

5.2 Main keys and keys combination function:

- [a↑] or [a↓] input distance (code 4)
- [b↑] or [b↓] input rim width (code 5)
- [d↑] or [d↓] input rim diameter (code 6)
- [SET] re-calculation
- [FINE] Show real imbalance amount
- [MODE] Function key of selecting balancing mode
- [FINE]+ [SET] Self-calibration
- [FINE]+ [a↑] + [a↓] conversion between gram and ounce
- [SET] + [MODE] Self-testing
- [FINE] + [MODE] Machine setting

NOTE:

1. After selection of gram or ounce , setting can remain after machine power off
2. Choose unit of mm for rim width and diameter, setting can not remain after machine power off

6. Installation and Demounting of the Wheel

6.1 Checking the wheel

The wheel must be clean, none sand or dust on it, and remove all the primal counterweights of the wheel. Check the tyre pressure whether up to the rated value. Check positioning plane of rim and mounting holes whether deformed.

6.2 Installing the wheel

6.2.1 Select the optimal cone for the center hole when there is center hole on the rim.

6.2.2 Two ways of installing the wheel: A. positive positioning; B. negative positioning.

6.2.2.1 Positive positioning (refer to Fig 6-1):

Positive positioning is commonly used. It operates easily, and it is applicable for various rims of common steel structure and thin duralumin structure.

6.2.2.2 Negative positioning (refer to Fig 6-2):

Negative positioning is used to ensure the inner hole of steel rim and main axis is positioning accurately when the outside of wheel deforming. Apply for all the steel rims, thick steel rims especially.

6.2.3 Install wheel and cone on main axis. Ensure the cone can clamp the wheel before screwing handle. Wheel can rotate after screwing down

6.3 Demounting the Wheel

6.3.1 Demount the handle and cone.

6.3.2 Put the wheel up, and then take it down from main axis.

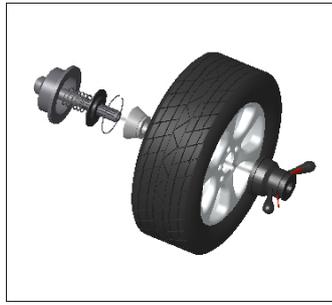


Fig 6-1



Fig 6-2

Note: do not slip wheel on main axis to prevent main axis from scuffing while installation and demounting the Wheel

7. The input methods of data of rim and balancing operation

7.1 The power-on state of the machine

After the power-on of the machine, it starts initialization automatically. The initialization will be finished after two seconds. The machine enters normal dynamic balancing mode (clamp counterweights on the both rim edge) automatically, as in Fig 7-1, ready for input data of rim



Fig 7-1

7.2 Data of wheel input method for normal dynamic balance mode and wheel balancing operation

7.2.1 After power is on, machine enters normal balancing mode, as below figure



7.2.2 Input rim data:

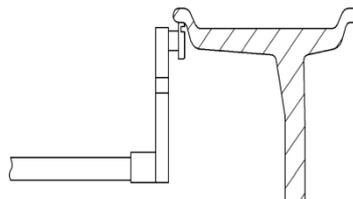


Fig 7-2

Move scale to make handle head touch rim edge inner position as Fig 7-2, get value a, put back scale. Push [a-] or [a+] to input a value

7.2.3 Input rim width

Get rim width data showing on rim, or measure rim width by caliper, push [b-] or [b+] to input b value

7.2.4 Input rim diameter

Get rim diameter data showing on rim, or measure rim diameter by caliper, push [d-] or [d+] to input d value

7.2.5 Balancing operation against normal dynamic balancing mode

Input rim data, manually rotate wheel, when display shows "RUN ---", move hand away to let wheel rotate. When display shows "STOP", wheel stops and display shows data.

Slowly rotate wheel, when inside position indication LEDs all light, (Fig 5-1 (10)), at the 12 o'clock position of rim inside , clamp weights equal to value shown on the left side display (Fig 7-3). Then slowly rotate wheel, when outside position indication LEDs all light, (Fig 5-1 (11)), at the 12 o'clock position of rim outside , clamp weights t equal to value shown on the right side display (Fig 7-4) . Rotate wheel by hand again, move hand away when display is off. When both side display are on, wheel stops and balancing is completed.



Fig 7-3



Fig 7-4

7.3 Static (ST) balancing mode data input method and balancing operation

(ST) mode is suitable for rims on which weights only can be stuck at middle position, such as motorcycle rims.

Under normal mode, measure diameter d value (Fig 7-5), press [d-] or [d+] to input d value. (a value and b value can be any value) . Press [MODE] key to make ST mode indication light on, enter static (ST) balancing mode, mode indication as following figure.

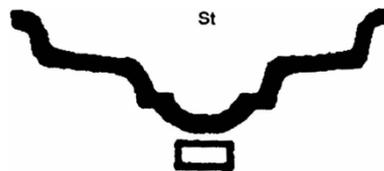


Fig 7-5

Input rim data, manually rotate wheel, when display shows "RUN ---", move hand away to let wheel rotate. Then right display shows ST and left display shows static imbalance amount as Fig 7-6. After wheel stops rotating, slowly rotate wheel, when inside position indication LEDs (Fig 5-1 (10)) and outside position indication LEDs (Fig 5-1 (11)) all light, stick weights equal to value shown on the left side display, at the 12 o'clock position of middle rim (Fig 7-5). Again manually rotate wheel, when display shows "RUN ---", move hand away to let wheel rotate. When both side display are on, wheel stops and balancing is completed.



Fig 7-6

7.4 ALU-1mode data input method and balancing operation

Follow 7.2 to input rim data, press [MODE] key, mode indication as below figure, then

enter ALU-1 mode to balance wheel



Input rim data, manually rotate wheel, when display shows “RUN ---”, move hand away to let wheel rotate. When display shows “STOP”, wheel stops and display shows data. Slowly rotate wheel, when inside position indication LEDs all light, (Fig 5-1 (10)), at the 12 o'clock position of rim inside edge , stick weights equal to value shown on the left side display (Fig 7-7 left) . Then slowly rotate wheel, when outside position indication LEDs all light, (Fig 5-1 (11)), at the 12 o'clock position of rim outside edge , stick weights equal to value shown on the right side display (Fig 7-7 right) . Rotate wheel by hand again, when display shows “RUN ---”, move hand away to let wheel rotate. When both side display are on, wheel stops and balancing is completed.

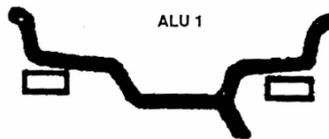


Fig 7-7

7.5 ALU-2 mode data input method and balancing operation

Follow 7.2 to input rim data, press [MODE] key, mode indication as below figure, then enter ALU-2 mode to balance wheel



Input rim data, manually rotate wheel, when display shows “RUN ---”, move hand away to let wheel rotate. When display shows “STOP”, wheel stops and display shows data. Slowly rotate wheel, when inside position indication LEDs all light, (Fig 5-1 (10)), at the 12 o'clock position of rim inside edge , stick weights equal to value shown on the left side display (Fig 7-8 left) . Then slowly rotate wheel, when outside position indication LEDs all light, (Fig 5-1 (11)), at the 12 o'clock position of rim inside , stick weights equal to value shown on the right side display (Fig 7-8 right) . Rotate wheel by hand again, when display shows “RUN ---”, move hand away to let wheel rotate. When both side display are on, wheel stops and balancing is completed



Fig 7-8

7.6 ALU-3 mode data input method and balancing operation

Follow 7.2 to input rim data, press [MODE] key, mode indication as below figure, then enter ALU-3 mode to balance wheel



Input rim data, manually rotate wheel, when display shows “RUN ---”, move hand away to let wheel rotate. When display shows “STOP”, wheel stops and display shows data. Slowly rotate wheel, when inside position indication LEDs all light, (Fig 5-1 (10)) , at the 12 o'clock position of rim inside edge , clamp weights equal to value shown on the left side display (Fig 7-9 left). Then slowly rotate wheel, when outside position indication LEDs all light, (Fig 5-1 (11)) , at the 12 o'clock position of rim inside , stick weights equal to value shown on the right side display (Fig 7-9 right) . Rotate wheel by hand again, when display shows “RUN ---”, move hand away to let wheel rotate. When both side display are on, wheel stops and balancing is completed

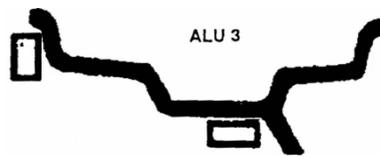


Fig 7-9

7.7 ALU-S mode data input method and balancing operation

Above three ALU modes may not be suitable for all structure rims. Balancing performance is not good under above three ALU modes for some rims. Then ALU-S mode can be adopted. Input rim data method as follows:

Press [MODE] key, to make ALU-S mode indication light on. Mode indication as following figure :



As per Fig 7-8 or Fig 7-9, move scale to rim inside (aI position), measure rim inner distance (aI) value, press [a-] or [a+] to input aI value

Move scale further inside to aE position, measure distance aE value, press [b-] or [b+]to input aE value

Measure rim diameter at aI position, press [d-] or [d+] to input dI value

Measure rim diameter at aE position, press [FINE] and [d-] or [d+] to input dE value

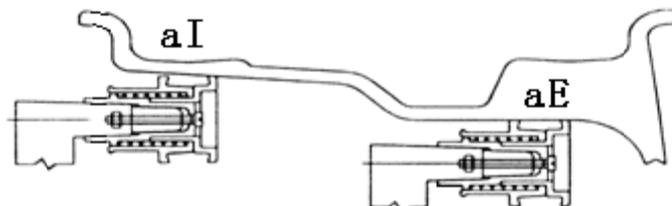


Fig 7-8

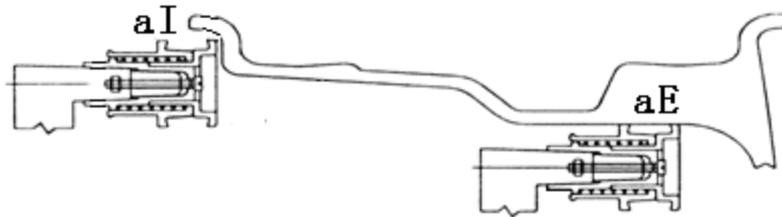


Fig 7-9

Input rim data, manually rotate wheel, when display shows “RUN ---”, move hand away to let wheel rotate. When display shows “STOP”, wheel stops and display shows data. Slowly rotate wheel, when inside position indication LEDs all light, (Fig 5-1 (10)), at the 12 o’clock position of rim inside aI position, stick weights equal to value shown on the left side display. Then slowly rotate wheel, when outside position indication LEDs all light, (Fig 5-1 (11)), at the 12 o’clock position of rim outside aE position, stick weights equal to value shown on the right side display. Rotate wheel by hand again, when display shows “RUN ---”, move hand away to let wheel rotate. When both side display show 0, balancing is completed

7.8 Counterweight split and Hidden-Stick Mode

This mode can split counterweights between two spokes into two section counterweight and the two section counterweights may be stuck behind two adjacent spokes so that counterweights are hidden . This mode is based on ALU-S mode.

Follow 7.7 operation, if outer side counterweight sticking position is not behind spokes, and user needs to hide counterweight behind spokes, user can operate as follows:

Press [FUNC] key, SPLIT indicator light (Fig 5-1 (16)) is on, spoke numbers inputting interface appears (Fig 7-10) . Press b+ or b- key to input spoke numbers, press [FUNC] key;



Fig 7-10

Slowly rotate wheel, make one piece spoke vertical upwards, press [FUNC] key

Slowly rotate wheel, find two imbalance positions following the imbalance position indication light, stick counterweights equal to two sections value at 12 o’clock position behind spokes. Quickly rotate wheel to balance wheel. Counterweights split and hidden operation is completed.

7.9 Recalculation

Before wheel balance testing, sometimes operator may forget input current data of rim. Data can be inputted after wheel balance testing. Then it is not necessary to make balancing test again. Operator only needs to press [SET] key, system can re-calculate imbalance value with new data. Under interface showing imbalance value, press [SET] key to check current inputted data of rim

8. Imbalance optimize

If wheel imbalance value over 30 gram, system will be display “OPT”, indicate to carry out

imbalance optimize

Imbalance optimize have two operation method:

8.1 Already display balance value

If already finish balance testing, when you need process imbalance optimize, press OPT key, display Fig 8-1;



Fig 8-1

Use chalk mark a reference point on the flange and rim and tyre, use tyre changer to exchange rim and tyre by 180°

Re-install wheel on the balancer and make sure mark of reference point between the flange and rim must be on the same position. Quickly rotate wheel to balance wheel, after rotation stop, display Fig 8-2;



Fig 8-2

As per above Fig 8-2, left display shows percent of optimize. If before optimize static value is 40 gram, optimized percent is 85%, so after optimize static value only 6 gram remain (15%×40gram=6gram);

Slowly rotate wheel by hand, when both end sides two of position indicator light flash (Fig 8-3), use chalk to make a mark on the tyre



Fig 8-3

Slowly rotate wheel by hand again, when both side middle position indicator light flash (Fig 8-4), use chalk to make a mark on the rim

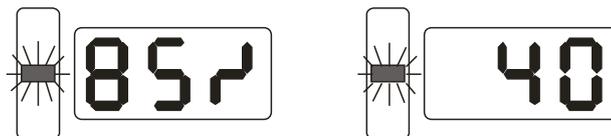


Fig 8-4

Demount wheel from balancer, use tyre changer to demount tyre from rim. Remount tyre on rim to make tyre and rim marks at same position. Optimize complete.

8.2 After power on and before balancing, also may process imbalance optimize directly

Turn on the power, install wheel, press OPT key, left side display shows OPT, quickly rotate wheel for balance testing. When rotation stops, display shows Fig 8-1, follow 8.1 operation. Press [SET] key to stop operation

9. Self-calibrating of Dynamic Balancer

The self-calibrating of dynamic balancer was finished before ex-factory, but the system parameter may vary because of long-distance transportation or long-term use, which may cause error. Therefore, users can make self-calibrating after a period of time.

9.1 After the power-on of the machine, the initialization is finished (Fig 7-1), install a middle size balanced rim which can be clamped with counterweight, follow 7.2 to input data of rim;

9.2 Press [FINE] + [SET] key (Fig 9-1), manually rotate wheel, when display is off, move hand away to let wheel rotate. When display shows "REDUCE", it means rotary speed is too faster now. When rotary speed reaches normal speed, display shows "RUN ---". When display shows "STOP", wheel stops rotating, display is as Fig 8-2. Press [SET] key to exit;



Fig 9-1

9.3 As per Fig 9-2, clamp a 100 gram counterweight on anywhere of outside of rim, manually rotate wheel, when display is off, move hands away to enter next step, Press [SET] key to exit;



Fig 9-2

9.4 As per Fig 9-3, wheel stops rotating, calibration ends. Demount tyre, now balancer is ready to work.



Fig 9-3

NOTE: when you doing self-calibration, input date of rim must be correct,100 gram counterweight must be correct, otherwise self-calibration result will be wrong, wrong self-calibration will be make balancer measure precision decline.

10. Gram-Oz conversion operation

This operation for counterweight weight unit conversion (gram-Oz)

10.1 Press [a-] or [a+] key, Fig 7-1;

10.2 Press [FINE] and hold it, then press [a+] and [a-] keys, weight unit is converted to Oz

10.3 Again press [FINE]+ [a+]+[a-] keys, weight unit is converted to Gram

10.4 Repeat 10.3 operation to convert weight unit between Gram and Oz

11. Other function settings

11.1 Minimum value display settings

Select minimum display value, if wheel imbalance value is less than setting value, displayed result will be 0. Press FINE key, real imbalance value can be shown.

Press [FINE] + [MODE] keys, show Fig11-1 which means if imbalance value is less than 5 gram, displayed result will be 0, press [b-] or [b+] key to set minimum display value : 5,10 or15. Press [a+] key to save current setting and enter next step.



Fig 11-1

11.2 Key-tone clue on function settings

This function can turn on or off key-tone. When turn on this function, every time press key, system will emit a “di” tone. When turn off this function, press key and there is no tone. Follow 10.1 and press [a+] key to enter, show Fig 11-2, right side display shows ON, means the function has been turned on. Display showing OFF means the function has been turned off. Press [b-] or [b+] key to shift function between “ON” and “OFF”. Press [a+] key to save current setting and enter next step.



Fig 11-2

11.3 Display monitor brightness settings

This function is for setting display brightness according working environment and user need

Follow 10.2 and press [a+] key to enter, show Fig 11-3, right side display shows brightness level. Totally 8 levels. Level 1 means dimmest display. Level 8 means brightest display. Default level is 4 . Press [b-] or [b+] key, to change levels. Press [a+] key to save current setting and enter next step .



Fig 11-3

11.4 INCH and MM conversion operation

Most rims has sizes unit INCH. If the unit is MM, system unit can be set to MM. If value has decimal, current unit is INCH. If value has no decimal , current unit is MM. This setting does not retain when machine is power off. System default unit is INCH

Follow 10.3, press [a+] key to enter (Fig 11-4), right side display shows ON, means unit is INCH,shows OFF, means unit is MM. Press [b-] or [b+] key, to shift “ON” and “OFF”. Press [a+] key to save current setting and exit.



Fig 11-4

12. Machine self test function

This function is for checking whether all inputted signals are normal and supports trouble analyses.

12.1 LED and indicator light check

Press [SET] + [MODE] keys, indicator light and LEDs light. This function can check whether LEDs or indicator light are damaged. Checking ends and display shows Fig 11-1. Enter position sensor signal check. Press [SET] key to exit.

12.2 Position sensor signal check

This function can check whether position sensor, main shaft, main board circuit are with

error. As per Fig 12-1, slowly rotate main shaft, value shown in right side display changes accordingly. Rotate clockwise, value increases; Rotate anticlockwise, value decreases. Normally, value changes among 0-63. Press [a+] key to enter press sensor signal check. Press [SET] key to exit.



Fig 12-1

12.3 Press sensor signal check

This function can check whether press sensor, main board signal circuit and power board are with error.

Follow 12.2 and press [a+] key to enter (Fig12-2). Then lightly press main shaft, if normally, values shown on display should be changed. Press [a+] or [SET] key to exit.



Fig 12-2

13. Trouble shooting

13.1 Manually rotate wheel to rating speed, LEDs are not off and balancing test is going on.

Computer board, position sensor and cables should be checked.

13.2 After machine power on, there is no display. Check power switch indicator light. If light is off, power supply gets problem. Otherwise, check power board, computer board and cables.

13.3 Inaccuracy of precision normally is not caused by balancer. It may be caused by wrong wheel installation, inaccurate counterweight or inaccurate 100g weight. The original 100g weight must be kept properly for self-calibration only

13.4 Unstable data and poor repeatability of data normally are not caused by balancer. It may be caused by wrong wheel installation or unstable installation of machine. Machine should be well fixed on ground by bolt.

Hint: check precision right method:

Input right date of wheel(a. b. d value), consult instruction do a self-calibration, process balance operation, note down date of first time, clamp 100 gram counterweight on the outside edge of wheel(when outside indicator light all on is top zenith position), again process balance operation, this data of outside display addition data of first time, should be 100 ± 2 , manually slowly rotate the wheel, when light of outside all on, check 100 gram counterweight whether at 6 o'clock position, if value is not 100 gram or 100 gram counterweight is not at 6 o'clock position, balancer precision has problem, if amount is 100 gram, follow same method check inside, check inside whether amount is 100 gram and at 6 o'clock.

14. Maintenance

14.1 The daily maintenance of non- professionals

Before the maintenance, please switch off the power-supply.

13.1.1 Check whether the wire of electricity part connects reliably.

13.1.2 Check whether the pressed screw of the main axis is loose

13.1.2.1 Locking nut can not fix wheel tighten on main-axis

13.1.2.2 Use hexagonal wrench to tighten the pressed screw of the main-axis.

14.2 The maintenance of professionals

The maintenance of professionals can only be carried out by the professionals from the factory

14.2.1 If the imbalance value of tested wheel has obvious errors and does not improve after self-calibrating, this proves the parameter in the machine has altered, so the user should ask for professionals

14.2.2 The replacing and adjustment of pressure sensor should be operated according to the following methods, and the operation should be carried out by professionals

The steps are as follows:

1. Unlash the No.1, 2,3,4,5 nuts.

2. Dismantle the sensor and nut.

3. Replace No.6, 7 the sensor organ.

4. Install the sensor and the nut according to the Fig 14-1. (Pay attention to the sensor's direction.)

5. Tighten No.1 nut emphatically.

6. Tighten the No.2 nut to make the main axis and the flank of cabinet, and then emphatically tighten the No.3 nut.

7. Tighten the No.4 nut (not too emphatically), then tighten No.5 nut.

14.2.3 The replacing of circuit board and the organ on it should be carried out by professionals

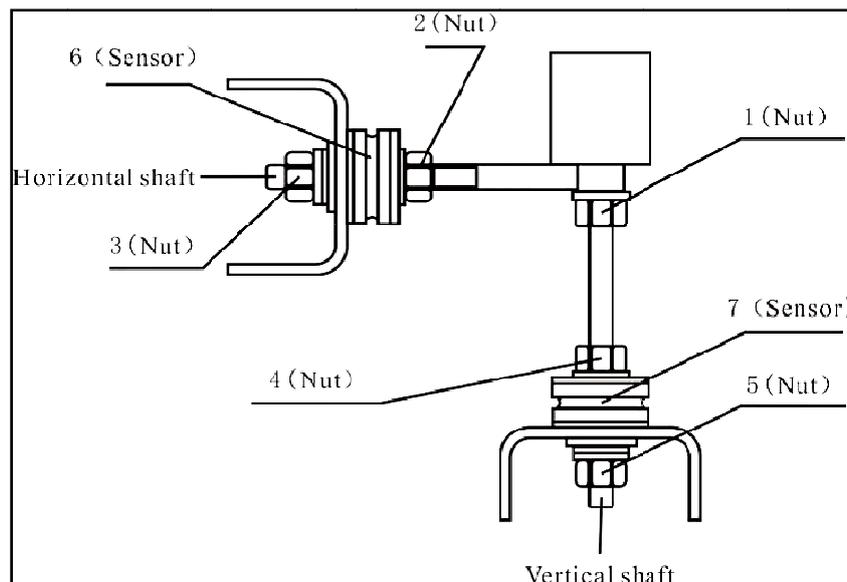


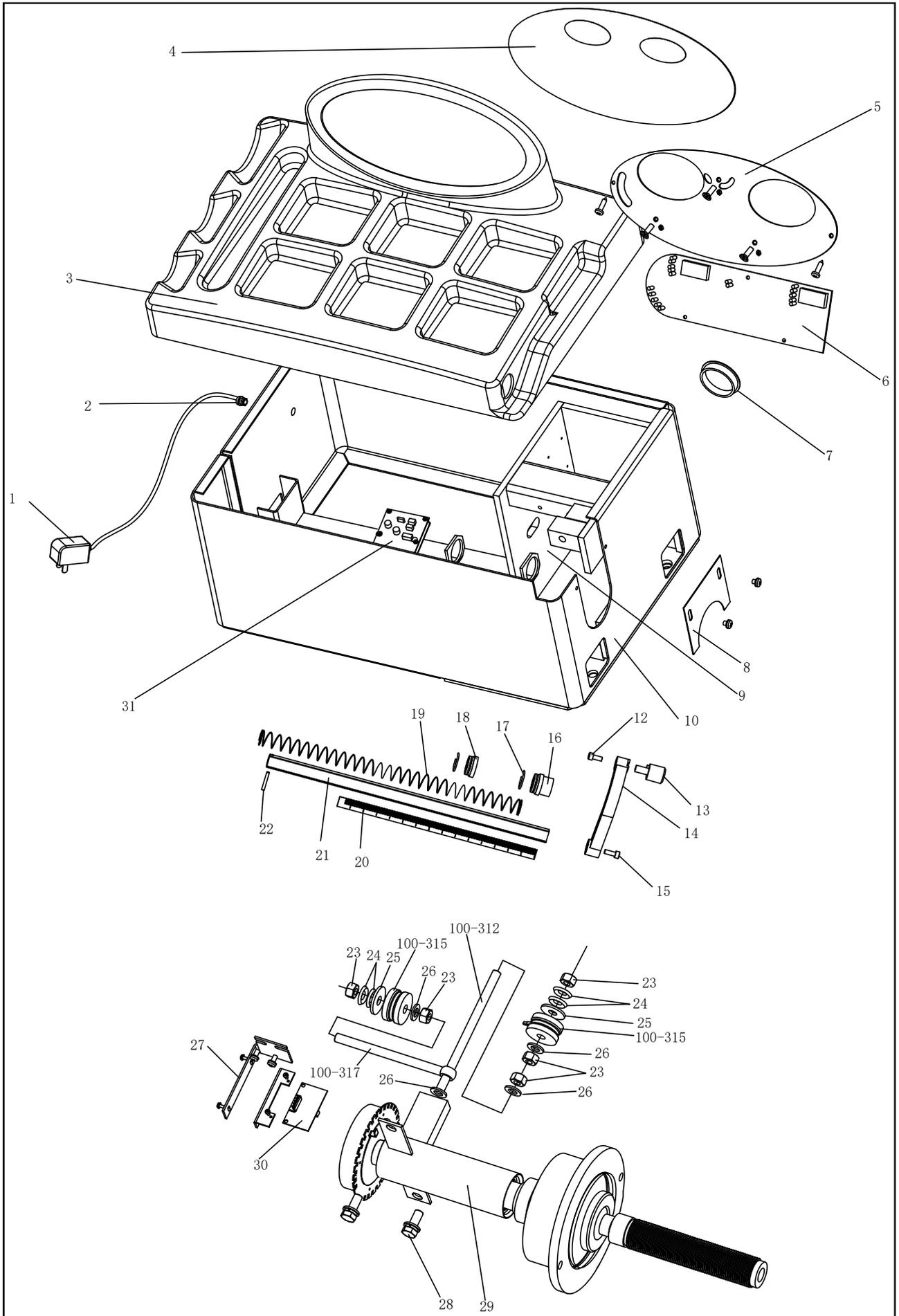
Fig14-1

15. Trouble-error code list

When balancer display hint of error, can follow consult below list to remove the trouble:

| Code | meanings | cause | remedy |
|-------|---|--|---|
| Err 1 | principal axis not spin or have not spin signal | 1. computer board fault 2. connection-peg untouched | 1. change computer board 2. check cable connections |
| Err 2 | The rotation speed is low | 1. position sensor fault 2. wheel not impacting or weight too light 3. computer board fault | 1. change position sensor 2. repeat impacting wheel 3. change computer board |
| Err 3 | Miscalculation | too high imbalance | Repeat the self-calibration or change computer board |
| Err 4 | principal axis wrong rotation direction | 1. position sensor fault 2. computer board fault | 1. change position sensor 2. change computer board |
| Err 6 | Sensor signal transact circuit not working | 1. power supply board fault 2. computer board fault | 1. change power supply board 2. change computer board |
| Err 7 | Lose date of interior | 1. Incorrect self-calibration 2. computer board fault | 1. Repeat the self-calibration 2. change computer board |
| Err 8 | Self-calibration memory fault | 1. not put 100 gram on the rim when self-calibration 2. power supply board fault 3. computer board fault 4. press sensor fault 5. connection-peg untouched | 1. follow right method repeat self-calibration 2. change power supply board 3. change computer board 4. change press sensor 5. check cable connection |

16. Exploded drawings



17. Spare parts list

| No. | Code | Description | Qt. | No. | Code | Description | Qt. |
|-----|-----------------|----------------------|-----|---------|-----------------|------------------------|-----|
| 1 | S-052-000012-0 | Power Adapter | 1 | 18 | P-100-170000-A | Plastic bush | 1 |
| 2 | | Power Interface | 1 | 19 | P-100-210000-0 | Spring | 1 |
| 3 | P-110-190000-0 | Head with tools-tray | 1 | 20 | Y-004-000070-0 | Graduated strip | 1 |
| 4 | S-115-001100-0 | Key board | 1 | 21 | P-100-900000-0 | Rim distance gauge | 1 |
| 5 | PX-110-110000-0 | Key fixed plate | 1 | 22 | B-061-004030-0 | Pin | 1 |
| 6 | PZ-000-010110-0 | Computer board | 1 | 23 | B-004-100001-2 | Nut | 5 |
| 7 | S-036-404500-0 | Plastic cover | 1 | 24 | B-048-102330-1 | Washer | 4 |
| 8 | PX-100-110000-0 | Plate | 1 | 25 | B-040-124030-1 | Washer | 1 |
| 9 | PX-110-010200-0 | Mounting base | 1 | 26 | B-040-102020-1 | Washer | 6 |
| 10 | PX-110-010000-0 | Chassis | 1 | 27 | PX-110-220000-0 | Support | 1 |
| | | | | 28 | B-014-100251-0 | Screw | 2 |
| 12 | B-024-050101-1 | Screw | 1 | 29 | S-100-000110-0 | Complete Shaft | 1 |
| 13 | P-100-160200-0 | Head | 1 | 30 | PZ-000-040110-0 | Position Pick-up Board | 1 |
| 14 | P-822-160100-0 | Handle | 1 | 31 | PZ-000-020110-0 | Power Board | 1 |
| 15 | B-010-060161-0 | Screw | 1 | 100-312 | P-100-080000-0 | Screw | 1 |
| 16 | P-100-170000-0 | Plastic bush | 1 | 100-315 | S-131-000010-0 | Sensor Assembly | 2 |
| 17 | P-100-520000-0 | Spring | 1 | 100-317 | P-100-070000-0 | Screw | 1 |